Execution Monitoring and Replanning

Section 12.5

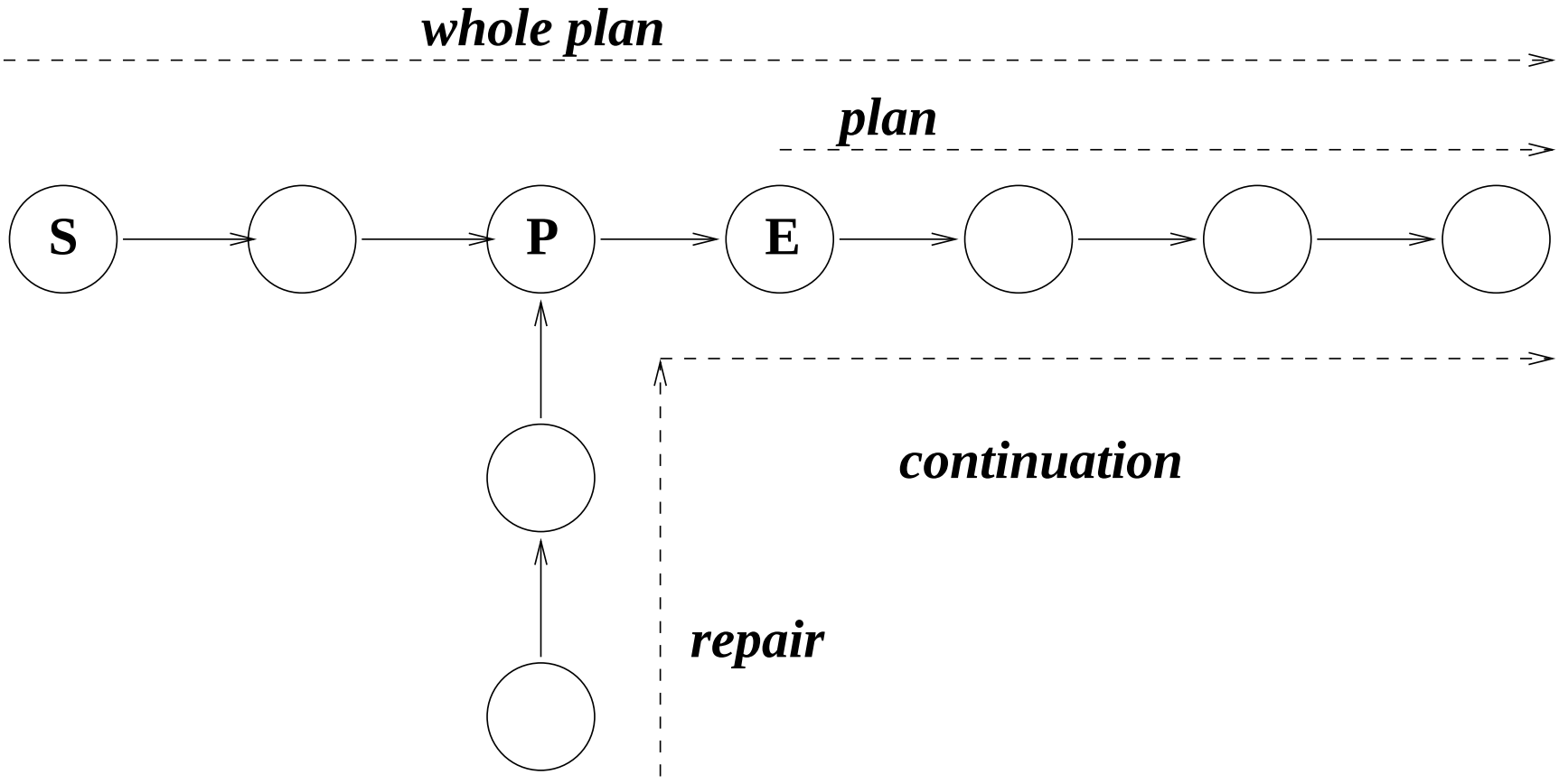
Outline

- Contingency planning vs. replanning
- Replanning agent algorithm
- Execution monitoring

Contingency planning vs. replanning

- *Contingency planning*: prepare in advance.
  Useful when some conditions needed for the contingency plan can be gathered before execution.
- *Execution monitoring*: ignore contingencies during planning, then handle them as they arise.
  Useful when planning time is a concern: not everything can be planned for.
- Basic idea: handle execution time failures at execution time.

Repairing a plan



Chair and table example

Init(Color(Chair,Blue) $\wedge$ Color Table(Green)
$\wedge$ ContainsColor(BC,Blue) $\wedge$ PaintCan(BC)
$\wedge$ ContainsColor(RC,Red) $\wedge$ PaintCan(RC))

Goal(Color(Chair,x) $\wedge$ Color(Table,x))

Action(Paint(object,color),
PRECOND: HavePaint(color)
EFFECT: Color(object,color))

Action(Open(can),
PRECOND: PaintCan(can) $\wedge$ ContainsColor(can,color)
EFFECT: HavePaint(color))

Chair and table example (cont'd)

Whole plan: [Start; Open(BC); Paint(Table,Blue); Finish]

What to do when

- it notices a missed green spot on the table just before finishing
- the agent plans to paint both red and it opens the can of red paint and finds there is only enough paint for the chair.

Algorithm

function REPLANNING AGENT(*percept*) **returns** an action
  static: *KB*, a knowledge base (includes action descriptions)
    plan, a plan, initially []
    whole-plan, a plan, initially []
    goal, a goal

  TELL (*KB*, MAKE-PERCEPT-SENTENCE (*percept,t*))
  current ← STATE-DESCRIPTION (*KB, t*)
  if *plan* = [] **then**
    whole-plan ← *plan* ← PLANNER(*current, goal, KB*)
  if PRECONDITIONS(FIRST (*plan*)) not currently true in *KB* then
    candidates ← SORT(*whole-plan*, ordered by distance to *current*)
    find state *s* in *candidates* such that
      failure ≠ *repair* ← PLANNER (*current,s,KB*)
    continuation ← the tail of *whole-plan* starting at *s*
    whole-plan ← *plan* ← APPEND(*repair, continuation*)
  return POP(*plan*)

What to monitor, what to ignore

- *Action monitoring:* Check the preconditions of the next action to execute
- *Plan monitoring:* Check the preconditions of all the actions to execute
- monitor a selected set based on priority
- Look for opportunities (*serendipity*)

Other important questions

- Which contingencies to plan for, which ones to leave until execution
- Should replanning be a plan step
- learning/modifying actions
- side note: “don’t touch” conditions