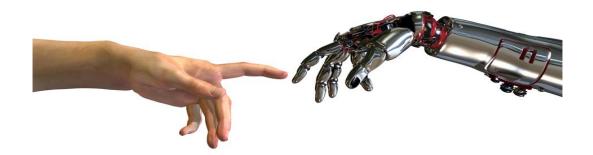
Human-Computer Interaction



Myounghoon "Philart" Jeon Mind Music Machine Lab Center of Cyber-Human Systems Cognitive Science, Computer Science

CS 1000 – October 13, 2015

Philart's Personal...











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Mind Music Machine



- 1 HCI Researcher @Daum Comm., UX/UI Designer & Sound Designer @LG Elec.
- 2 Co-work with SS, H/K Motors, Toyota, GE, Panasonic, etc.
- Best Papers (HFES, HCII), Ergonomic Design Award, IF Comm. Design Award
- HFES, CHI, HCII, MobileHCI, ASSETS, CSUN, ICAD, AutomotiveUI, UbiComp, etc.

Educational Background

PhD Engineering Psychology (HCI), Georgia Institute of Technology (2012)
M.S. Engineering Psychology, Georgia Institute of Technology (2010)
M.S. Cognitive Science, Yonsei University in Korea (2004)
B.A. Sociology, Yonsei University in Korea (2000)
B.A. Psychology, Yonsei University in Korea (2000)
Film Scoring Expert Institute, Yonsei University in Korea (2007)

Teaching

- Human-Computer Interaction/ HCD
- Affective Design and Computing
- Human Factors
- Human Factors II: Multimodal Design & Measure Studio





What type of produ[je]cts?

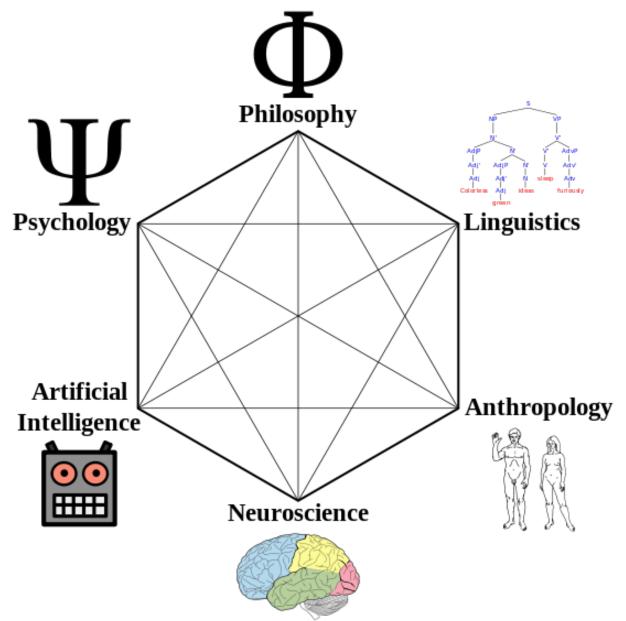






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Academic Origin: Cognitive Sciences (Cognitive Engineering)







In fact, Affective Sciences











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The tri-M Lab



6 + 2 Graduates (Human Factors + Computer Science) 8 Undergraduates (CS, CE, Psy, Sound Design, ME)





Center of Cyber-Human Systems, Institute of Computing and Cybersystems ${}^{>\!\!\!\!/}$

Human-Centered Design: Designing systems of the users, by the users, and for the users. We are interested in People, Art, Design, Technology, & eXperiences



entered



Computing

UGMENTED & VIRTUAL REALITY

Human-Centered Design Promoting a harmonious existence with technological systems



FFECTIVE

COMPUTING

SSISTIVE TECHNOLOGY

UTOMOTIVE UI

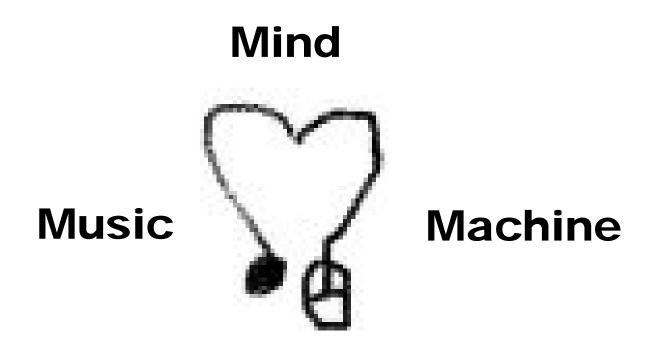




Mind Music Machine

The tri-M Lab

Google "mind music machine lab" Or email <u>philart@gmail.com</u> or mjeon@mtu.edu









Sonification in VR Goal

Expand artists' emotional expressions and aesthetic dimensions using visualization and sonification at the immersive virtual environment



System Configuration

Vicon Tracker – 12 infrared cameras

- 120 Hz
- Sub-millimeter precision
- Display Wall 24, 42'' Monitors
- OpenGL (C++)
- JFugue Library for audio output
- ISML GUI interface for customizing sonification par ameters







System Configuration

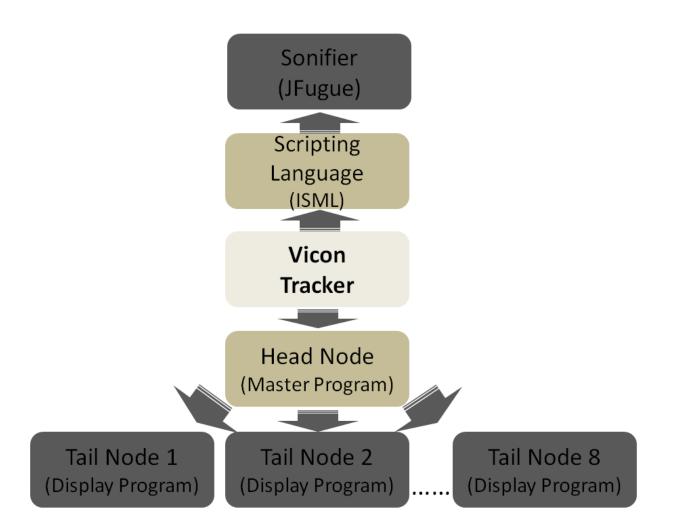
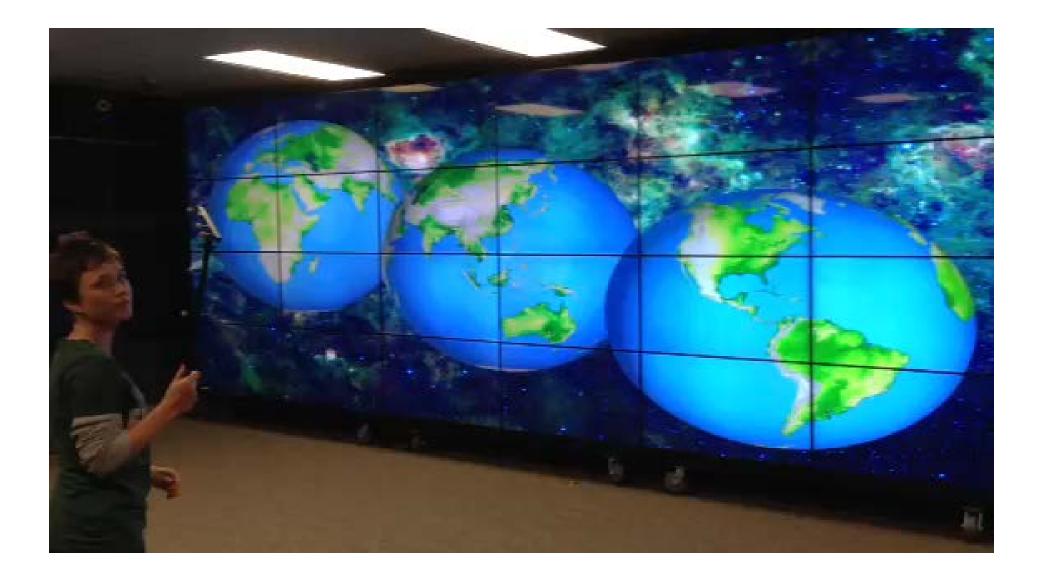


Fig. 1. The Vicon tracker sends the signal to (1) the visualizer (head node), which distributes it to 8 tail nodes, each of which is connected to 3 multivisions; and (2) the sonifier via the scripting language.





Interactive Map

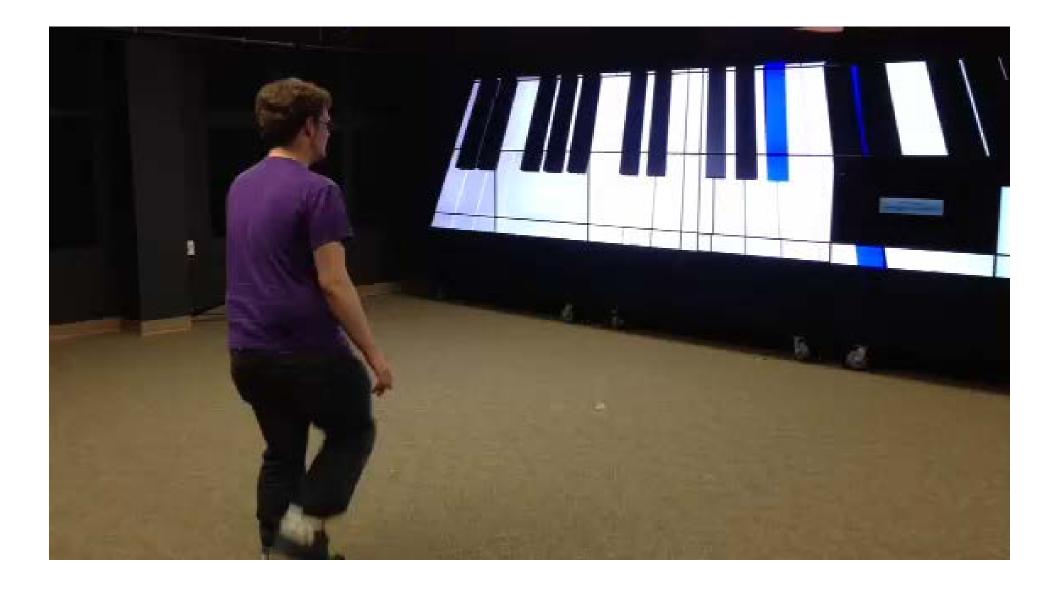






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Virtual Instrument







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Tony Orrico...



Tony Orrico, 8 circles | Photo by Michael Hart

Based in Chicago, creates large geometric pieces, "Penwald Drawings"







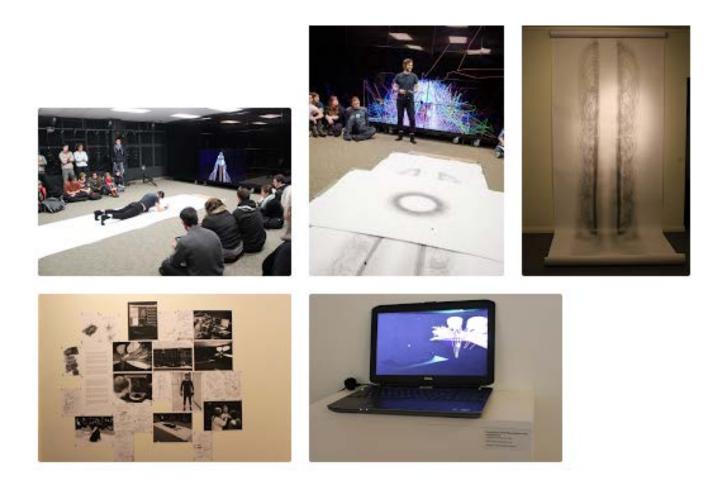
Embodied Penwald Drawings

"Orrico laid face down on a piece of paper holding graphite pencils in both hands. He pushed off a wall, jetting himself forward on top of the piece. He dragged his graphite pencils along with him; as he writhed his way back to the starting position over and over again, he left behind himself a pictorial history of his motion."

"He knelt on a large sheet of paper, striking it with graphite as he swung his arms in a pendular motion, and slowly revolved atop the mat."



Multiple Layers of Outcomes



The outcomes of our collaboration and Tony's works were displayed in the Finnish American Heritage Center in Hancock, MI.



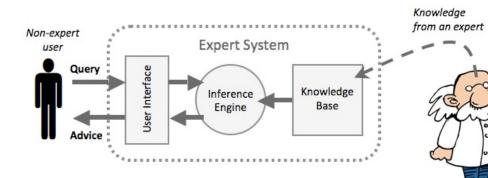


Research in Progress

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Creativity & Intentionality









Automotive User Interfaces & ITS

01. Warning Design

02. Social Car

03. Emotional Driving





Goal

Taking drivers' emotions and affect into account, improve road safety by estimating a driver's affective states and intervening with dynamic technologies



Driving Simulators in tri-M Lab

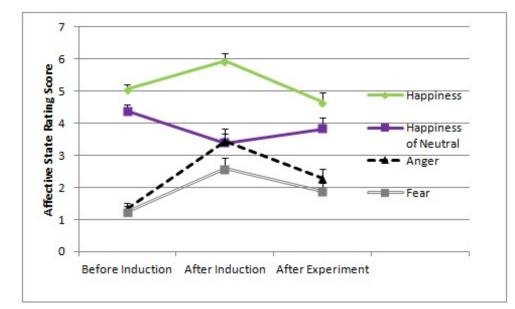


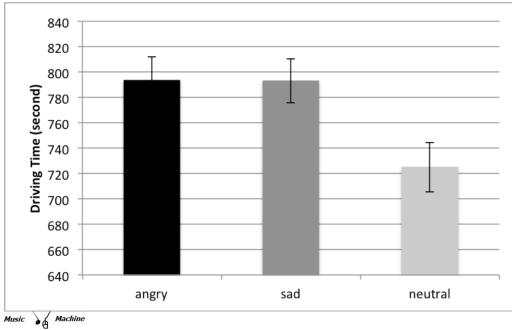


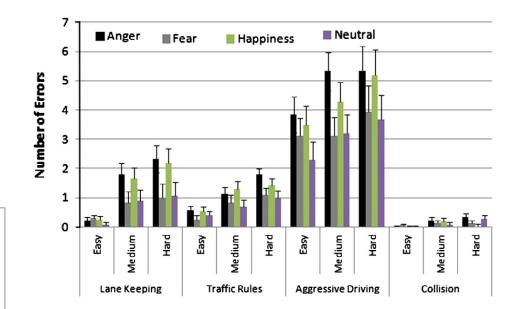
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Results from 8 Experiments



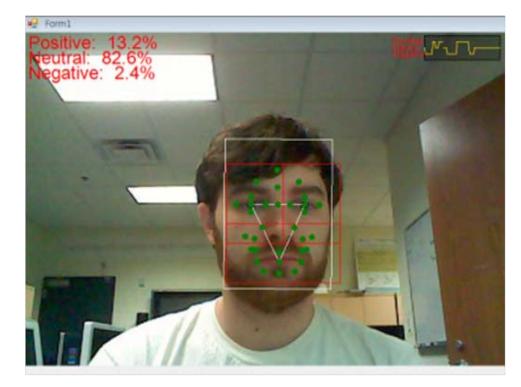






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Facial Expression Detection Systems



Our first system uses the Support-Vector Machines (SVMs) algorithm, which could detect positive, negative, and neutral affective states. Our second system uses the Viola–Jones object detection framework, which could detect more specific affective states, including anger, happiness, and surprise. •••• AT&T 🤶 2:30 PM annt

Start capture Stop capture Graph





Research in Progress

Table 2. Mapping variables for observation states and sonification parameters

Observation States		Sonification Parameters (SP
Affective States (AS)	Driving Behaviors (DB)	
 FacialExpression: s_{FEX} FacialEMG: s_{FEMG} EyeMovementPattern: s_{EMP} HeartRate: s_{HR} Respiration: s_{RE} SkinConductance: s_{SC} BrainWaves: s_{EEG} 	 LaneDeviation: s_{LD} SteeringWheelAngle: s_{SWA} Speed: s_{SP} Pedal Force: s_{PF} Collision: s_{CO} 	Musical Parameters (MP) - Genre: c_{GE} - Key: c_{KEY} - Tempo: c_{TE} Human Factors (HF) - Familiarity: c_{FA} - Preference: c_{PR} - Expectation: c_{EX} System Factors (SF) - Timing: c_{TI} - Duration: c_{DU} - Regularity: c_{RE} - Interference: c_{IN}

ObservationStates = $AS(s_{FEX,} s_{FEMG,} s_{EMP,} s_{HR,} s_{RE,} s_{SC,} s_{EEG}) \times DB(s_{LD,} s_{SWA,} s_{SP,} s_{PF,} s_{CO})$ SonificationParameters = $MP(c_{GE,} c_{KEY,} c_{TE}) \times HF(c_{FA,} c_{PR}, c_{EX}) \times SF(c_{TI,} c_{DU,} c_{RE,} c_{IN})$ SonificationOutputs = $f(ObservationStates \times SonificationParameters)$

Intermittent sonification based on driver affective states and behaviors

Continuous sonification using multistream soundscapes







Assistive Technologies & Accessible Computing 01. Navigation for Blind 02. Digital Literacy for OAs 03. SocialBot for Autism



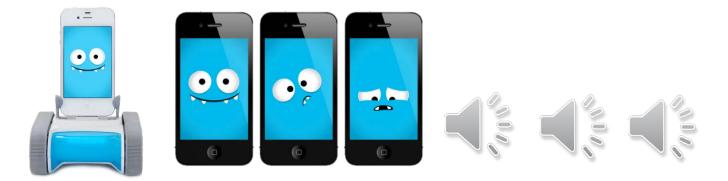


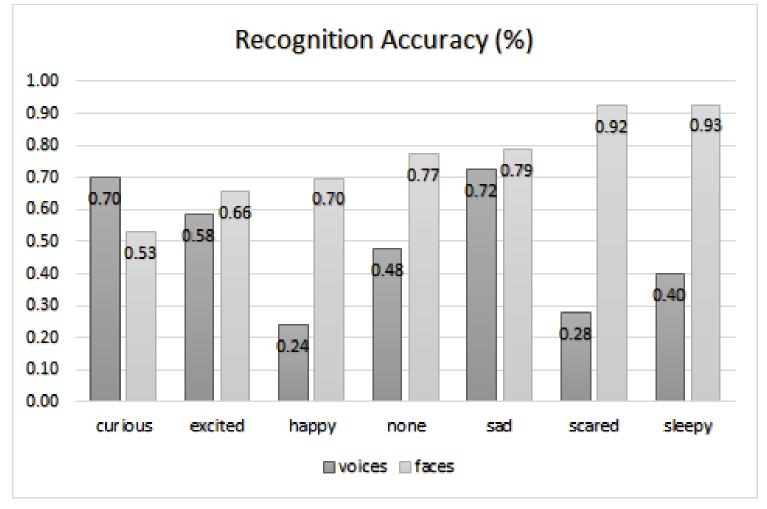
Goal

Facilitate social and emotional interaction of children with ASD using physical and musical stimuli



Emotion Recognition Research



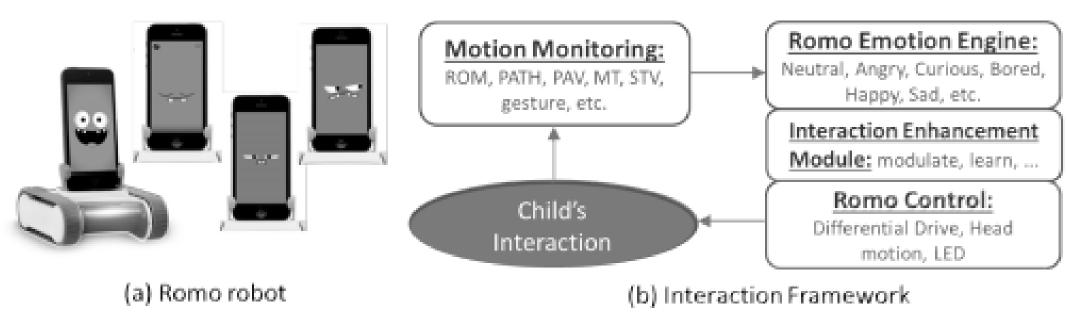


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Research Concept Diagram



Research Aspects

Platform-free sonification server
 Estimation a child's affective sates and overall interaction patterns with a robot
 Robotic learning of human behaviors for increasing the

Research in Progress









Research: Robot Acceptance Human-Robot Team Interaction









Thank You

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